

Notice of References Cited	Application/Control No. 10/821,423		Applicant(s)/Patent Under Reexamination WALTERS ET AL.	
	Examiner CUONG H. NGUYEN		Art Unit 3661	Page 1 of 2

U.S. PATENT DOCUMENTS

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Name	Classification
	A	US-			
	B	US-			
	C	US-			
	D	US-			
	E	US-			
	F	US-			
	G	US-			
	H	US-			
	I	US-			
	J	US-			
	K	US-			
	L	US-			
	M	US-			

FOREIGN PATENT DOCUMENTS

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Country	Name	Classification
	N					
	O					
	P					
	Q					
	R					
	S					
	T					

NON-PATENT DOCUMENTS

*		Include as applicable: Author, Title Date, Publisher, Edition or Volume, Pertinent Pages)
*	U	Command, control, and navigation experimental results with the NPS ARIES AUV; Marco, D.B.; Healey, A.J.; Oceanic Engineering, IEEE Journal of; Volume 26, Issue 4, Oct. 2001 Page(s):466 - 476; Digital Object Identifier 10.1109/48.972079
*	V	Location-based services: advances and challenges; Adusei, I.K.; Kyamakya, K.; Erbas, F.; Electrical and Computer Engineering, 2004. Canadian Conference on; Volume 1, 2-5 May 2004 Page(s):1 - 7 Vol.1
*	W	The vSLAM Algorithm for Robust Localization and Mapping; Karlsson, N.; di Bernardo, E.; Ostrowski, J.; Goncalves, L.; Pirjanian, P.; Munich, M.E.; Robotics and Automation, 2005. ICRA 2005. Proceedings of the 2005 IEEE International Conference on; 18-22 April 2005 Page(s):24 - 29
*	X	Team TerraMax and the DARPA grand challenge: a general overview; Ozguner, U.; Redmill, K.A.; Broggi, A.; Intelligent Vehicles Symposium, 2004 IEEE; 14-17 June 2004 Page(s):232 - 237; Digital Object Identifier 10.1109/IVS.2004.1336387

*A copy of this reference is not being furnished with this Office action. (See MPEP § 707.05(a).)
Dates in MM-YYYY format are publication dates. Classifications may be US or foreign.

Notice of References Cited	Application/Control No. 10/821,423		Applicant(s)/Patent Under Reexamination WALTERS ET AL.	
	Examiner CUONG H. NGUYEN		Art Unit 3661	Page 2 of 2

U.S. PATENT DOCUMENTS

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Name	Classification
	A	US-			
	B	US-			
	C	US-			
	D	US-			
	E	US-			
	F	US-			
	G	US-			
	H	US-			
	I	US-			
	J	US-			
	K	US-			
	L	US-			
	M	US-			

FOREIGN PATENT DOCUMENTS

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Country	Name	Classification
	N					
	O					
	P					
	Q					
	R					
	S					
	T					

NON-PATENT DOCUMENTS

*		Include as applicable: Author, Title Date, Publisher, Edition or Volume, Pertinent Pages)			
*	U	Holographic navigation; Rikoski, R.; Brown, D.; Robotics and Automation, 2008. ICRA 2008. IEEE International Conference on 19-23 May 2008 Page(s):73 - 80; Digital Object Identifier 10.1109/ROBOT.2008.4543189			
*	V	Rapid world modelling from a mobile platform; Barry, R.E.; Jones, J.P.; Little, C.Q.; Wilson, C.W.; Robotics and Automation, 1997. Proceedings., 1997 IEEE International Conference on; Volume 1, 20-25 April 1997 Page(s):72 - 77 vol.1; Digital Object Identifier 10.1109/ROBOT.1997.620018			
*	W	Performance of an AUV navigation system at Arctic latitudes; McEwen, R.; Thomas, H.; OCEANS 2003. Proceedings; Volume 2, 22-26 Sept. 2003 Page(s):642 - 653 Vol.2; Digital Object Identifier 10.1109/OCEANS.2003.1283346			
*	X	Command, control, and navigation experimental results with the NPS ARIES AUV; Marco, D.B.; Healey, A.J.; Oceanic Engineering, IEEE Journal of; Volume 26, Issue 4, Oct. 2001 Page(s):466 - 476; Digital Object Identifier 10.1109/48.972079			

*A copy of this reference is not being furnished with this Office action. (See MPEP § 707.05(a).)
Dates in MM-YYYY format are publication dates. Classifications may be US or foreign.